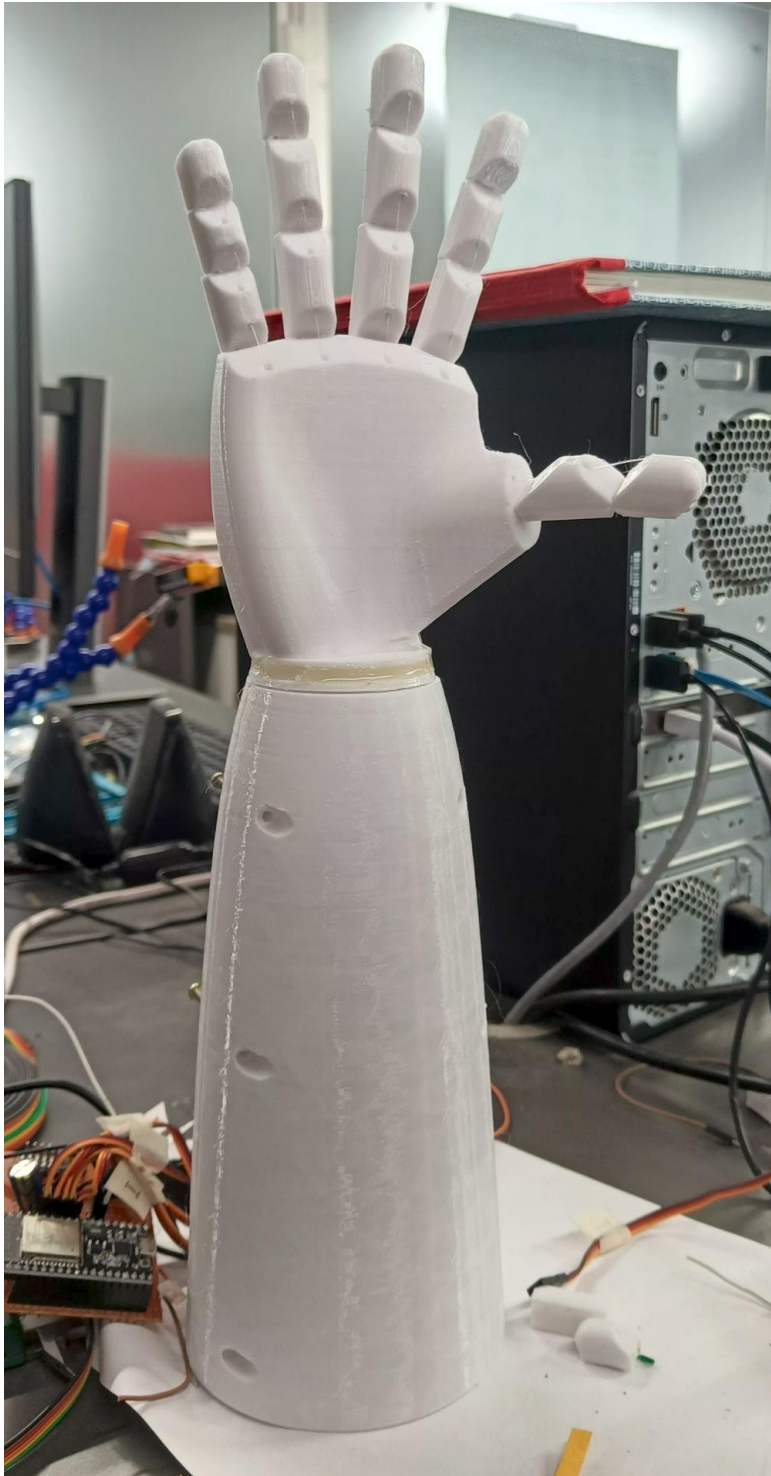


Bionic Hand



A robotic hand designed to mimic the movements of a human hand. It consists of five servo motors controlling five fingers and is operated using a sensor-equipped glove that captures the user's hand movements in real time. The project demonstrates human-machine interaction and can be used in prosthetic research, rehabilitation systems, robotic manipulation, and remote operation applications.